

Deep Inference Proof Systems for Monotone Quantifiers

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1 Proof Theory of Generalized Quantifiers

- Rules for Quantifiers ?
- Monotonicity and Deep Inference

2 System QC

- Rules and Derivations
- Properties

3 Extensions and Applications

- Extending QC
- n -ary Quantifiers
- Notable Quantifier Classes

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Generalized Quantifiers

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Well-known extension of usual quantification: quantifier $\approx$ relation on relations.

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A quantifier of type $\langle k_1, \dots, k_n \rangle$ takes n formulae as arguments, and binds k_n variables in each formula:

$$Q\vec{x}_1, \dots, \vec{x}_n[\varphi_1(\vec{x}_1), \dots, \varphi_n(\vec{x}_n)]$$

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Interpreted in a model $\mathcal{M}$ by $\llbracket Q \rrbracket^{\mathcal{M}} \subseteq \mathcal{P}(\mathcal{M}^{k_1}) \times \dots \times \mathcal{P}(\mathcal{M}^{k_n})$:

$$\mathcal{M} \models Q\vec{x}_1, \dots, \vec{x}_n[\varphi_1, \dots, \varphi_n]$$

iff

$$(\llbracket \varphi_1 \rrbracket^{\mathcal{M}}, \dots, \llbracket \varphi_n \rrbracket^{\mathcal{M}}) \in \llbracket Q \rrbracket^{\mathcal{M}}$$

Generalized Quantifiers

Rules for Quantifiers ?

Examples:

- $\exists$ is the type $\langle 1 \rangle$ quantifier defined by the unary relation "being non-empty":

$$\llbracket \exists \rrbracket^{\mathcal{M}} = \{X \in \mathcal{P}(\mathcal{M}) \mid X \neq \emptyset\}$$

- "Most X are Y" is the type $\langle 1, 1 \rangle$ quantifier:

$$\llbracket Most \rrbracket^{\mathcal{M}} = \{(X, Y) \in \mathcal{P}(\mathcal{M}) \times \mathcal{P}(\mathcal{M}) \mid |A \cap B| > |A - B|\}$$

- Henkin quantifiers, e.g. with type $\langle 4 \rangle$:

$$\llbracket \left(\begin{smallmatrix} \forall x & \exists y \\ \forall u & \exists v \end{smallmatrix} \right) \rrbracket^{\mathcal{M}} = \{R \in \mathcal{P}(\mathcal{M}^4) \mid \exists f \exists g \forall x \forall u, (x, y, f(x), g(y)) \in R\}$$

- Many, many more...

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Very good notions of semantics, very poor notions of proofs *in general*.

Proof Rules for Quantifiers

Rules for Quantifiers ?

The usual quantifiers have very convenient introduction/elimination rules e.g.

$$\exists \frac{A(t)}{\exists x A(x)} \quad \forall \frac{A(x)}{\forall x A(x)}, \text{ with } x \text{ eigenvariable}$$

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Generalized quantifiers have no such rules in general.

Example (Keisler) : "uncountably many" $Q^{>\omega}$:

$$\times \frac{A(t)}{Q^{>\omega} x [A(x)]} \quad \times \frac{Q^{>\omega} x [A(x)]}{A(t)}$$

are not valid rules.

What can we do ?

Rules for Quantifiers ?

A valid pseudo-syllogism:

Most C are A

All A are B

∴ Most C are B

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Rules for Quantifiers ?

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Most C are A
All A are B
 $\therefore$ *Most C are B*

Similarly, this is one of Keisler's Axioms for $Q^{>\omega}$:

$$\forall x[A(x) \rightarrow B(x)] \rightarrow (Q^{>\omega}x[A(x)] \rightarrow (Q^{>\omega}x[B(x)]))$$

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$$\forall x[A(x) \rightarrow B(x)] \rightarrow (Q^{>\omega}x[A(x)] \rightarrow (Q^{>\omega}x[B(x)]))$$

In other terms, if $\frac{A(x)}{B(x)}$ is a valid inference, then so are :

$$\frac{Most_x [C(x), A(x)]}{Most_x [C(x), B(x)]} \quad \text{and} \quad \frac{Q^{>\omega}x [A(x)]}{Q^{>\omega}x [B(x)]}$$

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$$Most_x \left[C(x), \frac{A(x)}{B(x)} \right] \quad \text{and} \quad Q^{>\omega}x \left[\frac{A(x)}{B(x)} \right]$$

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Monotonicity and Deep Inference

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Alternatively, if you see logics as categories, they are the quantifiers that are *functors*.

Monotone quantifiers

Monotonicity and Deep Inference

In a model, logical consequence becomes subset inclusion: entailment-preserving quantifiers are exactly *monotone quantifiers*.

Definition

- Q is *monotone increasing* in an argument i if for all $(A_1, \dots, A_n)$ and $B \supseteq A_i$, $(A_1, \dots, A_i, \dots, A_n) \in \llbracket Q \rrbracket$ implies $(A_1, \dots, B_i, \dots, A_n) \in \llbracket Q \rrbracket$.
- Q is *monotone decreasing* in an argument i if for all $(A_1, \dots, A_n)$ and $B \subseteq A_i$, $(A_1, \dots, A_i, \dots, A_n) \in \llbracket Q \rrbracket$ implies $(A_1, \dots, B_i, \dots, A_n) \in \llbracket Q \rrbracket$.

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Increasing quantifiers preserve derivations, and decreasing quantifiers "invert" derivations by switching premiss and conclusion.

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Increasing quantifiers preserve derivations, and decreasing quantifiers "invert" derivations by switching premiss and conclusion.

Increasing quantifiers are functors, decreasing quantifiers are contravariant functors.

Definition

For a given argument i , we say that a quantifier Q is:

- 1 i -positive if for all φ_j , $Q\vec{x}[\dots, \varphi_{i-1}, \top, \varphi_{i+1}, \dots] \equiv \top$.
- 2 i -negative if for all φ_j , $Q\vec{x}[\dots, \varphi_{i-1}, \perp, \varphi_{i+1}, \dots] \equiv \top$.
- 3 i -anti-positive if for all φ_j , $Q\vec{x}[\dots, \varphi_{i-1}, \top, \varphi_{i+1}, \dots] \equiv \perp$.
- 4 i -anti-negative if for all φ_j , $Q\vec{x}[\dots, \varphi_{i-1}, \perp, \varphi_{i+1}, \dots] \equiv \perp$.

Quantifier Polarity

Monotonicity and Deep Inference

Definition

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Polarity essentially describes how quantifiers behave on $\top$ and $\perp$.

Useful to turn derivations into proofs, similar to the usual equalities:

$$\forall x. \top = \top = \exists x. \top$$

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We give a formalization of the *Quantifier Calculus* QC , for monotone/polarized quantifiers:

- Built on the formalism of *Open Deduction*.
- Monotonicity allows inferences within quantifiers.
- Polarity gives us axioms to close proofs.

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- Built on the formalism of *Open Deduction*.
- Monotonicity allows inferences within quantifiers.
- Polarity gives us axioms to close proofs.

For brevity, we present a version with unary (type $\langle k \rangle$) quantifiers, but the n -ary case is similar.

Formulae and Derivations

Rules and Derivations

Usual first-order language, extended with monotone quantifiers $\mathcal{L}(\mathcal{Q}_1, \mathcal{Q}_2, \dots)$. Formulae $\mathcal{F}$ and terms t are defined by:

$$t ::= x \mid c \mid f(t, \dots, t)$$

$$\mathcal{F} = \top \mid \perp \mid p(t, \dots, t) \mid \bar{p}(t, \dots, t) \mid \mathcal{F} \vee \mathcal{F} \mid \mathcal{F} \wedge \mathcal{F} \mid \mathcal{Q} \vec{x}[\mathcal{F}]$$

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Negation as De Morgan dualities:

$$\overline{\top} = \perp \quad \overline{\perp} = \top \quad \overline{p(t_1, \dots, t_n)} = \bar{p}(t_1, \dots, t_n)$$

$$\overline{A \wedge B} = \bar{A} \vee \bar{B} \quad \overline{A \vee B} = \bar{A} \wedge \bar{B} \quad \overline{\mathcal{Q} \vec{x}[A]} = \mathcal{Q}^d \vec{x}[\bar{A}]$$

where the *dual* $\mathcal{Q}^d$ is defined as $\mathcal{Q}^d \vec{x}[A] = \overline{\mathcal{Q} \vec{x}[\bar{A}]}$.

Equational Theory of QC

Rules and Derivations

$$A \vee \perp = A \quad A \wedge \top = A \quad \top \vee \top = \top \quad \perp \wedge \perp = \perp$$

$$A \wedge B = B \wedge A \quad A \vee B = B \vee A$$

$$A \wedge (B \wedge C) = (A \wedge B) \wedge C \quad A \vee (B \vee C) = (A \vee B) \vee C$$

$$Q\vec{x}[\top] = \top \text{ if } Q \text{ is positive} \quad Q\vec{x}[\perp] = \top \text{ if } Q \text{ is negative}$$

$$Q\vec{x}[\top] = \perp \text{ if } Q \text{ is anti-positive} \quad Q\vec{x}[\perp] = \perp \text{ if } Q \text{ is anti-negative}$$

Inference Rules of QC

Rules and Derivations

$$i\downarrow \frac{\top}{A \vee \overline{A}}$$

$$i\uparrow \frac{A \wedge \overline{A}}{\perp}$$

$$s \frac{(A \vee B) \wedge C}{A \vee (B \wedge C)}$$

$$qs \frac{Q\vec{x}[A(\vec{x}) \vee B] \wedge C}{Q\vec{x}[A(\vec{x}) \wedge C] \vee B}$$

$$w\downarrow \frac{\perp}{A}$$

$$w\uparrow \frac{A}{\top}$$

$$= \frac{A}{B}$$

$$qmix \frac{Q\vec{x}[A(\vec{x}) \wedge B] \wedge \overline{C}}{Q\vec{x}[A(\vec{x}) \vee C] \vee \overline{B}}$$

$$c\downarrow \frac{A \vee A}{A}$$

$$c\uparrow \frac{A}{A \wedge A}$$

$$\text{if } A = B$$

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- If $\frac{A}{B} \Pi, \frac{C}{D} \Delta$ are derivations and $\rho \frac{B}{C}$ is a rule, then $\rho \frac{\Pi}{\Delta}$ is a derivation $\frac{A}{D}$.

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- If $Q^\uparrow$ is an increasing quantifier and $\frac{A}{B}$ is a derivation, then $Q^\uparrow \vec{x} \left[\frac{A}{B} \right]$ is a derivation with premiss $Q^\uparrow \vec{x} [A]$ and conclusion $Q^\uparrow \vec{x} [B]$.

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- If $Q^\downarrow$ is a decreasing quantifier and $\frac{A}{B}$ is a derivation, then $Q^\downarrow \vec{x} \left[\frac{A}{B} \right]$ is a derivation with premiss $Q^\downarrow \vec{x} [B]$ and conclusion $Q^\downarrow \vec{x} [A]$.

Theorem

If there is a derivation $\frac{A}{B}$, then $A \models B$. In particular, if a formula is provable then it is valid.

Proof.

By induction on derivations. The soundness of the composition of derivations by a quantifier is a consequence of monotonicity. □

Examples

Properties

For any *increasing* quantifier $Q^\uparrow$, the rule $\text{qc}^\uparrow \frac{Q^\uparrow \vec{x}[A(\vec{x}) \wedge B(\vec{x})]}{Q^\uparrow \vec{x}[A(\vec{x})] \wedge Q^\uparrow \vec{x}[B(\vec{x})]}$ is admissible:

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$$\begin{array}{c}
 Q^\uparrow \vec{x} [A(\vec{x}) \wedge B(\vec{x})] \\
 \hline
 c\uparrow \frac{}{Q^\uparrow \vec{x} \left[\frac{A(\vec{x}) \wedge \boxed{w\uparrow \frac{B(\vec{x})}{\top}}}{A(\vec{x})} \right] \wedge Q^\uparrow \vec{x} \left[\frac{\boxed{w\uparrow \frac{A(\vec{x})}{\top}} \wedge B(\vec{x})}{B(\vec{x})} \right]}
 \end{array}$$

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Properties

For any *decreasing* quantifier $Q^\downarrow$, the rule $\text{dq}\downarrow \frac{Q^\downarrow \vec{x} [A(\vec{x}) \vee B(\vec{x})]}{Q^\downarrow \vec{x} [A(\vec{x})] \wedge Q^\downarrow \vec{x} [B(\vec{x})]}$ is admissible:

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For any *decreasing* quantifier $Q^\downarrow$, the rule $\text{dq}\downarrow \frac{Q^\downarrow \vec{x} [A(\vec{x}) \vee B(\vec{x})]}{Q^\downarrow \vec{x} [A(\vec{x})] \wedge Q^\downarrow \vec{x} [B(\vec{x})]}$ is admissible:

$$c\uparrow \frac{Q^\downarrow \vec{x} [A(\vec{x}) \vee B(\vec{x})]}{Q^\downarrow \vec{x} \left[\frac{A(\vec{x})}{A(\vec{x}) \vee \boxed{w\downarrow \frac{\perp}{B(\vec{x})}}} \right] \wedge Q^\downarrow \vec{x} \left[\frac{B(\vec{x})}{\boxed{w\downarrow \frac{\perp}{A(\vec{x})}} \vee B(\vec{x})} \right]}$$

Remark that since $Q^\downarrow$ is decreasing, the inner derivations are "upside-down".

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Adding specific rules

Extending QC

System QC is designed to be as generic as possible, and does not account for particular properties of specific quantifiers.

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If there is the need, we can add to QC any rule $\frac{F}{G}$, under the condition that it is *locally sound*, i.e. for all $\mathcal{M}$, $\mathcal{M} \models F$ implies $\mathcal{M} \models G$.

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If there is the need, we can add to QC any rule $\frac{F}{G}$, under the condition that it is *locally sound*, i.e. for all $\mathcal{M}$, $\mathcal{M} \models F$ implies $\mathcal{M} \models G$.

Examples of rules that are globally sound, but not locally sound are typically rules with side conditions:

$$\forall \frac{A(x)}{\forall x A(x)}, \text{ with } x \text{ eigenvariable}$$

Example

Extending QC

For example, we can reintroduce the instantiation rule for $\exists$: $n\downarrow \frac{A(t)}{\exists x A(x)}$ and use it within other quantifiers:

$$\text{qs} \frac{
 \begin{array}{c}
 \top \\
 \hline
 Q^{\uparrow}y \left[\begin{array}{c}
 \text{i}\downarrow \frac{\top}{A(y) \vee \begin{array}{c} n\downarrow \frac{\overline{A}(y)}{\exists x \overline{A}(x)} \end{array}} \end{array} \right] \\
 \hline
 \exists x \overline{A}(x) \vee Q^{\uparrow}y[A(y)]
 \end{array}
 }{=}$$

$$\text{qmix} \frac{
 \begin{array}{c}
 \top \\
 \hline
 Q^{\downarrow}y \left[\begin{array}{c}
 \overline{\exists x A(x)} \wedge \begin{array}{c} n\downarrow \frac{A(y)}{\exists x A(x)} \end{array} \\
 \text{i}\uparrow \frac{}{\perp}
 \end{array} \right] \\
 \hline
 \exists x A(x) \vee Q^{\downarrow}y[A(y)]
 \end{array}
 }{=}$$

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The rules q_s and q_{mix} are also sound in their n -ary version:

$$q_s \frac{Q\vec{x}[\dots, A(\vec{x}) \vee B, \dots] \wedge C}{Q\vec{x}[\dots, A(\vec{x}) \wedge C, \dots] \vee B}$$

$$q_{mix} \frac{Q\vec{x}[\dots, A(\vec{x}) \wedge B, \dots] \wedge \overline{C}}{Q\vec{x}[\dots, A(\vec{x}) \vee C, \dots] \vee \overline{B}}$$

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Example: $More_x[A, B]$, with $\llbracket More \rrbracket = \{(A, B) \mid |A| \geq |B|\}$

$More$ is 1-increasing, 2-decreasing, and for any A , $More_x[A(x), A(x)] = \top$.

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 \top \\
 \hline
 = \frac{}{More_x \left[\begin{array}{c} \frac{}{A(x)} \\ \hline \frac{}{\downarrow i} \frac{\top}{B(x) \vee \overline{B}(x)} \wedge A(x) \\ \hline B(x) \vee \frac{}{\downarrow n} \frac{A(x) \wedge \overline{B}(x)}{\exists y[A(y) \wedge \overline{B}(y)]} \end{array} , \frac{}{\begin{array}{c} C(x) \wedge \frac{}{\uparrow n} \frac{\forall y[\overline{C}(y) \vee A(y)]}{\overline{C}(x) \vee A(x)} \\ \hline \frac{}{\uparrow i} \frac{C(x) \wedge \overline{C}(x)}{\perp} \vee A(x) \\ \hline A(x) \end{array} } \right]} \\
 \text{qs} \frac{}{\exists y[A(y) \wedge \overline{B}(y)] \vee More_x[B(x), C(x) \wedge \forall y[\overline{C}(y) \vee A(y)]]} \\
 \text{qmix} \frac{}{\exists y[\overline{C}(y) \wedge \overline{A}(y)] \vee \exists y[A(y) \wedge \overline{B}(y)] \vee More_x[B(x), C(x)]}
 \end{array}$$

is a proof of:

$$\forall y[C(y) \rightarrow A(y)] \wedge \forall y[A(y) \rightarrow B(y)] \rightarrow More_x[B(x), C(x)]$$

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- Quantifiers "more than κ ", "less than κ " for any cardinal κ , strict or not.

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Notable cases of application:

- All Henkin Quantifiers and their duals are increasing, positive and anti-negative.
- Quantifiers "more than κ ", "less than κ " for any cardinal κ , strict or not.
- The majority of natural language quantifiers are monotone in at least one argument, e.g. "most", "more ... than ...", "almost all", "many", "few", etc.

Monotone Quantifier Classes

Notable Quantifier Classes

Notable cases of application:

- All Henkin Quantifiers and their duals are increasing, positive and anti-negative.
- Quantifiers "more than κ ", "less than κ " for any cardinal κ , strict or not.
- The majority of natural language quantifiers are monotone in at least one argument, e.g. "most", "more ... than ...", "almost all", "many", "few", etc.
- Conjunctions and disjunctions of increasing (resp. decreasing) quantifiers are also increasing (resp. decreasing). Negation reverses monotonicity.

- QC is a baseline sound proof system for the broadest class of quantifiers suitable for deep inference: monotone quantifiers.

Perspectives

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- Do usual structural properties hold ?
 - Locality
 - Cut-elimination/normalization
 - Decomposition theorems

Thank you for your attention !